

# Long Time Series Measurements of Munitions Mobility in the Wave-Current Boundary Layer

MR-2320

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U.S. Naval Research Laboratory

In-Progress Review Meeting

15 May 2018



# MR-2320: Mobility and Burial Measurements

**Performers:** Joe Calantoni (U.S. Naval Research Laboratory)

## Technology Focus

- Evaluating suite of instrumentation to make high fidelity, long-term observations of hydrodynamic forcing, sedimentology, and munitions mobility and burial including "Smart Munitions"

## Research Objectives

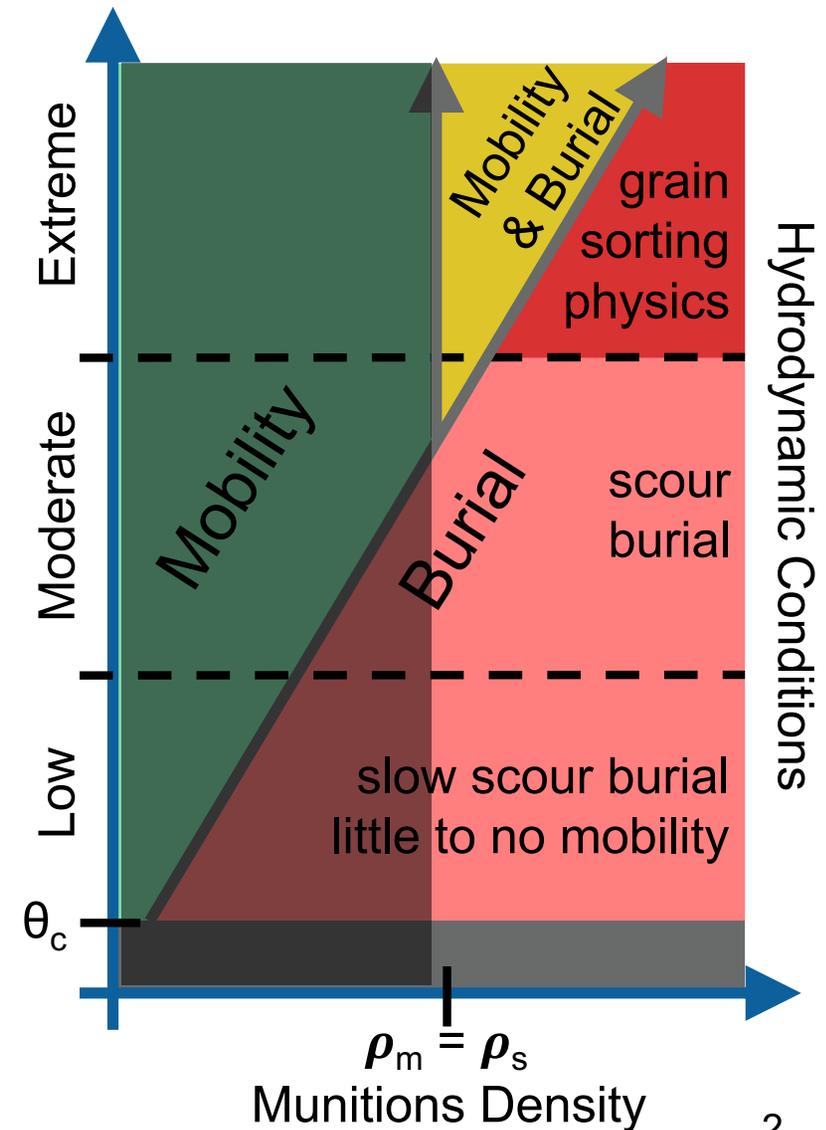
- Our objective is to provide in situ time series measurements of boundary layer hydrodynamics while simultaneously monitoring the resulting mobility and burial of munitions

## Project Progress and Results

- Executed three field experiments for range of conditions
- Quantified the role of munitions bulk density on mobility and burial for range of munitions characteristics in situ
- Directly measured munitions bulk density for 70 items
- Developed sediment instability model for extreme burial
- Correlated statistics of mobility to water wave statistics in situ

## Technology Transition

- Prepare and distribute documentation for all aspects of experimental methods, including design, fabrication, deployment, recovery, and signal processing
- Complete and distribute database of munitions characteristics including estimates of bulk density distributions
- Reduce dimensionality of the problem regarding munitions characteristics and environmental forcing conditions



# Social Media Content



**Joe Calantoni**

**NRL Sediment Dynamics Section, Research Physicist**

***Underwater munitions bury in the sand...** Joe Calantoni from the U.S. Naval Research Laboratory performs a tabletop demonstration to explain the physics of munitions burial in underwater environments. As water waves grow large during storms they generate momentary failure of the sand bed. The physics of granular sorting determines whether munitions will bury or rise to the surface.*

## Project Team

- PI, Joe Calantoni (U.S. Naval Research Laboratory)
- Co-PI, Alex Sheremet (University of Florida)

### Other significant contributors:

- Ed Braithwaite, Blake Landry, Christy Swann, Sam Bateman, Ryan Mieras\*, Jan Watkins\*, Donya Frank\*, Adam Seyfarth\*\*, & Rob Hagg\*\* (NRL)
- Harald Klammler\*, Tracy Staples & Uriah Gravois (UF)
- Diane Foster & Meagan Wengrove (UNH)
- Jesse McNinch (USACE)
- Carter Duval (UD)

# Problem Statement

- Needs in the underwater environment include:
  - Assess predict location of munitions relative to the bed
  - Assess environment where munitions are found
- Need to couple munitions mobility with hydrodynamic & sedimentary processes
- Environmental forecasting critical for optimizing sensor performance



23 April 2014

<http://www.dailymail.co.uk/travel/article-2611037/Mappleton-beach-cordoned-Second-World-War-bomb-blown-EIGHT-rockets-sands.html>

## Technical Objective

Our objective is to provide in situ time series measurements of boundary layer processes responsible for munitions mobility while simultaneously monitoring the mobility of surrogate munitions.

# Technical Approach Overview

- Observations guided by hypothesis for the conditions that favor munitions mobility versus burial *in situ*
- Developed / fabricated / deployed
  - ◆ Range of munitions caliber (20 mm – 155 mm)
  - ◆ Range of munitions density (plastic to steel)
  - ◆ Smart surrogates (embedded IMU)
- Executed three field experiments (7 m – 20 m depths)
  - ◆ Apr-May 2013 at Panama City Beach, FL (sandy; max  $h_s = 2$  m)
  - ◆ Jan-Mar 2015 at Duck, NC (sandy; max  $h_s = 5$  m)
  - ◆ Feb-Apr 2017 at Wallops Island, VA (mixed; max  $h_s = 3$  m)
- Performed measurements of bulk density of surrogate and inert munitions at Blossom Point Facility (Dec 2016)
  - ◆ Produce probability distributions for range of munitions density

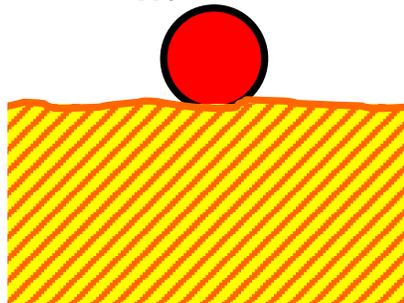
# Mobility versus Burial Hypothesis

Cartoon on the role of relative density for munitions mobility and burial in sandy sedimentary environments

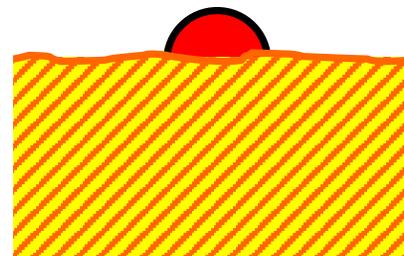
relative density,  $s_m$ , is the ratio of density of munitions to the density of sediment

$$s_m = \frac{\rho_m}{\rho_s}$$

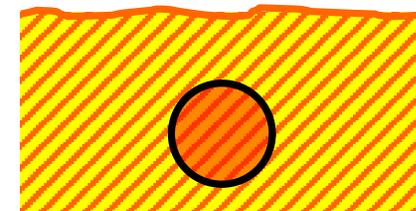
$$s_m < 1$$



$$s_m \approx 1$$



$$s_m > 1$$



**MOBILITY**



**BURIAL**

(see “Why the Brazil Nuts are on Top...”, Rosato et al., *Physical Review Letters*, 1987; “Reverse Brazil Nut Problem...”, Hong et al., *Physical Review Letters*, 2001)

# Fabricated Surrogate Munitions



- 20 mm to 155 mm calibers
- Included shape effects
- Range of bulk densities
- Range of rolling moments
- Attached acoustics pingers



# Surrogate Smart Munitions



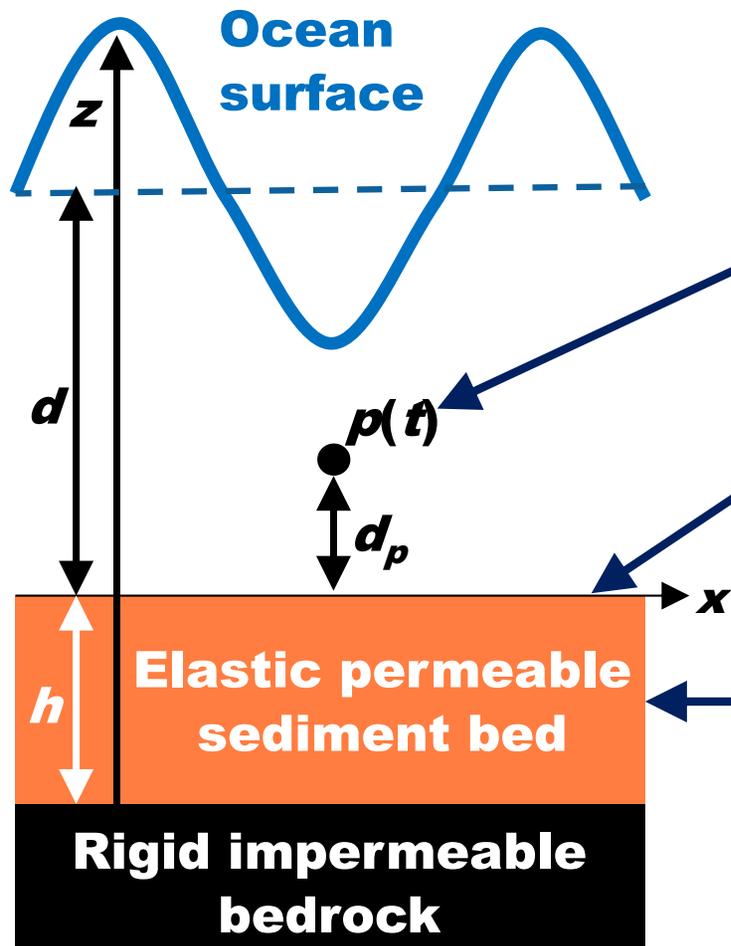
# Field Instrumentation



## Results Overview

- Applied wave-induced sediment instability analysis to TRENCH data set
- Refined method for determining range of munitions bulk density using Army Technical Manuals
- Wallops Island munition mobility analysis

# Wave-induced Sediment Instability Analysis



## Observed pressure

$$p(t) = \sum_{m=1}^M a_m \cos(-\omega_m t + \varepsilon_m)$$

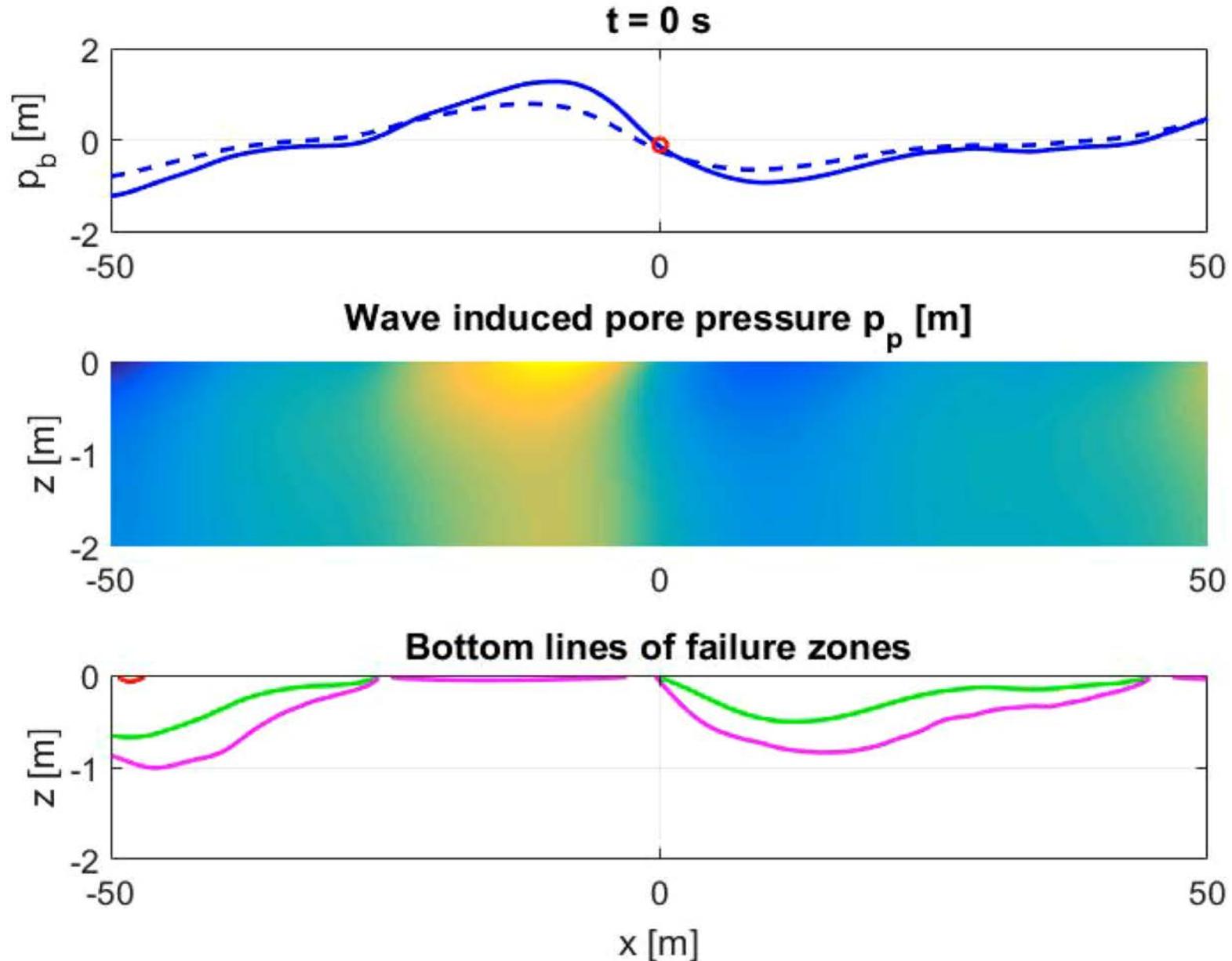
## Pressure distribution at seabed

$$p_b(x, t) = \sum_{m=1}^M \frac{a_m}{\cosh k_m d_p} \cos(k_m x - \omega_m t + \varepsilon_m)$$

## Sediment pore pressure and effective stresses

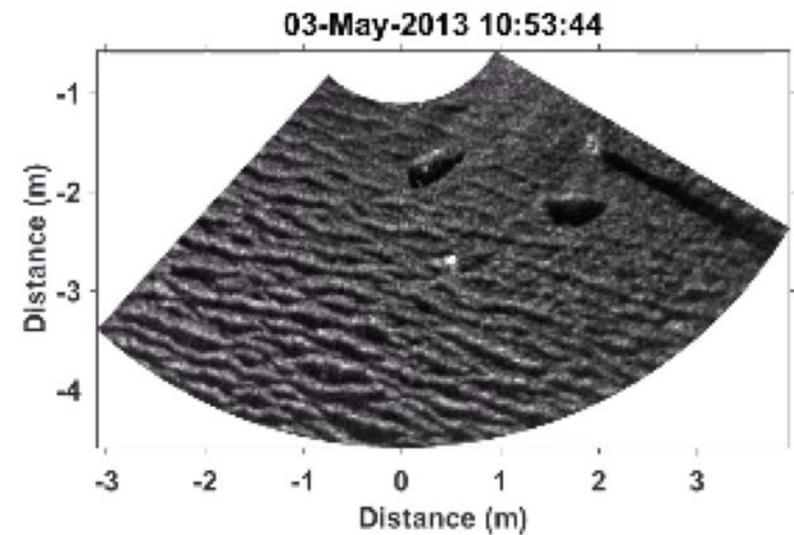
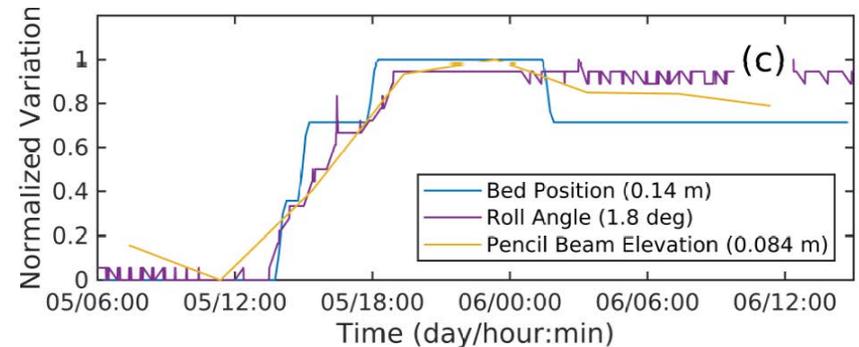
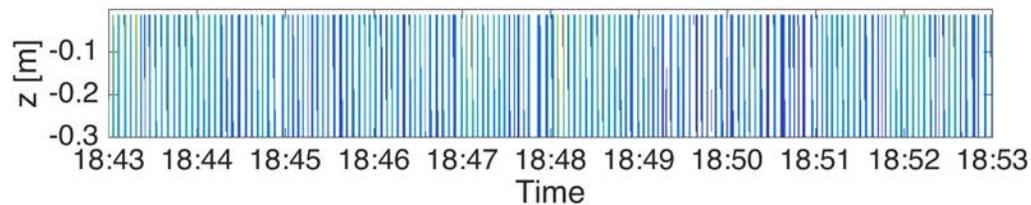
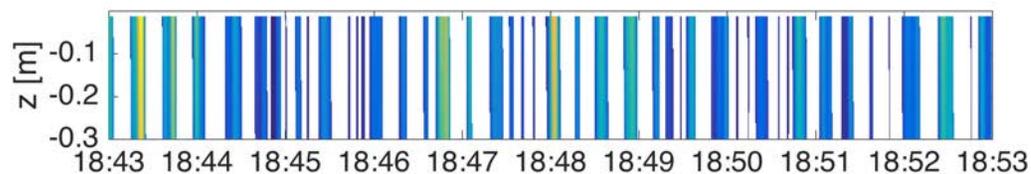
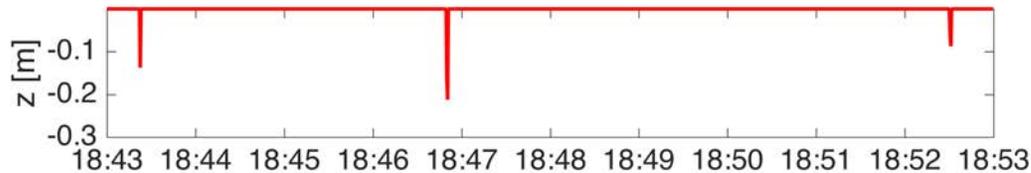
$p_p$ ,  $\sigma'_x$ ,  $\sigma'_z$  and  $\tau_{xz}$  result as functions of  $x$ ,  $z$  and  $t$

# Predicted Bed Failure during Duck 2015



# Predicting Bed Failure during TRES

- Analysis explains sinking of quadpod instrument platform

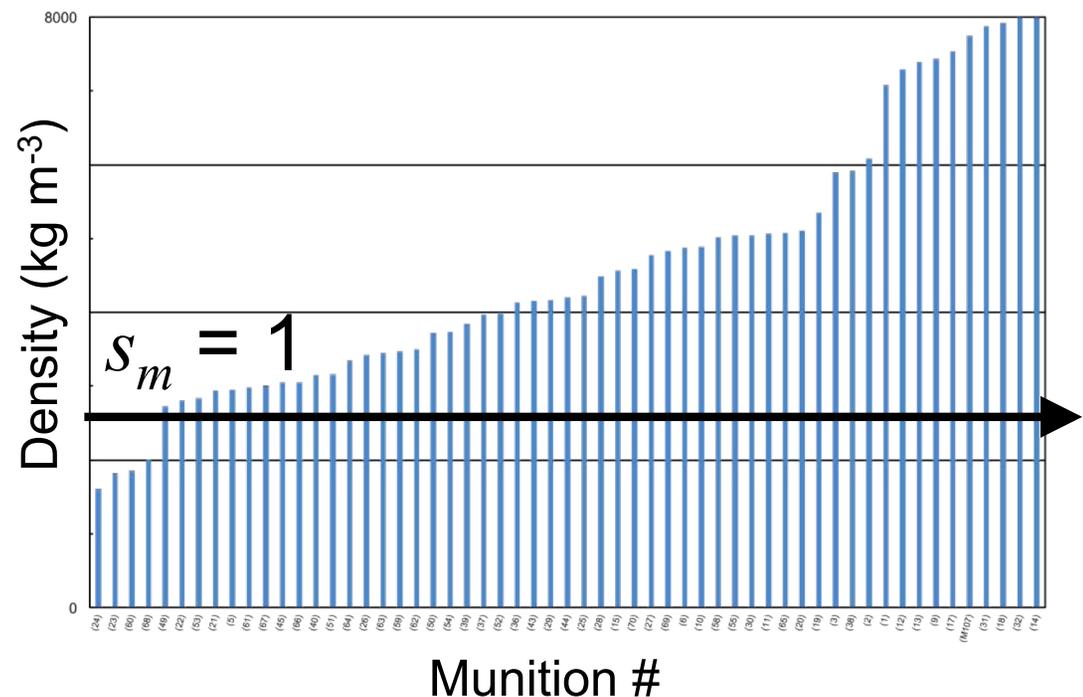


# Measured Density of Munitions



- Interrogated 70 items in the inert/surrogate inventory at Blossom Point, MD
  - Items range from inert certified UXO to simple pipe surrogates
- Weighed items → MASS estimates
- 3D laser scans and hand measurements used to build CAD models → VOLUME estimates

$$\text{DENSITY} = \frac{\text{MASS}}{\text{VOLUME}}$$



# Estimating Weight Range of Munitions

## 155mm M116

- Army Ammunition Data Sheet
  - ◆ Technical Manual 43-0001-28
- Each munition has “options”
  - ◆ Weight zones/ranges
  - ◆ Filler materials
  - ◆ Fuze types
- Data extracted from the manual is copied into a JSON database with a standardized format
- Each munition has a distribution of possible weights, computed by combinatorial expansion of the possible “options”

TM 43-0001-28

**Difference Between Models:**  
 The expelling charge in Model M116B1 (0.34 lb of black powder) is contained in a polyethylene cup instead of in a cloth bag as in M116 (0.29 lb of black powder). Also, the copper closure disk used in Model M116 has been replaced with a steel disk in the newer model.

**Temperature Limits:**  
 Firing: Lower limit ----- -40°F (-40°C)  
 Upper limit ----- +125°F (+52.0°C)  
 Storage: Lower limit ----- -80°F for periods not more than 3 days (-62.2°C)  
 Upper limit ----- +160°F for periods not more than 4 hr/day (+71.1°C)  
 \*Packing ----- 8 projectiles on pallet  
 \*Pallet: Colored Smoke Loaded HC 727 lb 802 lb  
 Weight 27-1/8 X 27-1/8 X 13-5/8 X 13-5/8 X 32 in. 32 in. 6.8 cu ft 6.8 cu ft

**Tabulated Data:**

Zone	Over Pounds	Up To & Incl Pounds	Marking (Zone squares)
2	90.7	92.0	□ □
3	91.8	93.1	□ □ □
4	92.7	94.4	□ □ □ □
5	94.0	95.3	□ □ □ □ □

Weight Zone applies to HC canister loaded projectiles without fuze, lifting plug, gasket and grommet.

**Complete round:** Type ----- Smoke HC or colored  
 Weight as fired: HC ----- 94.80 lb  
 Colored ----- 86.23 lb  
 Length without lifting plug ----- 30.9 in. nominal  
 Cannon used with ----- M1, M1A1, M1A2, M45, M126, M126A1, M185

**Projectile:** Material ----- Forged steel  
 Newer-Light green w/black markings  
 (Colored smoke - Color indicated by a series of 3 C's) Older - Gray w/yellow markings  
 Filler and weight ----- HC, 25.84 lb  
 Colored smoke: 17.19 lb  
 Propelling charge ----- M3/M4 series

**Primers:** ----- MK2A4 (M1, M1A1, M1A2, M45 cannon) M82 (M126, M126A1, M185)

**Fuzes:** ----- MTSQ, M501 series

**Shipping and Storage Data:**  
 Quantity-distance class ----- 1.3  
 Storage compatibility group -- G  
 DOT shipping class ----- B  
 DOT decimation ----- SPECIAL FIREWORKS, HANDLE CAREFULLY, KEEP FIRE AWAY  
 DODAC: HC ----- 1320-D548  
 Red ----- 1320-D549  
 Yellow ----- 1320-D551  
 Green ----- 1320-D547  
 Violet ----- 1320-D554  
 Assembly Dwg No. ----- 9227998  
 UNO serial number ----- 0016  
 UNO proper shipping name --- Ammunition, smoke

**Ballistics:**  
 Cannon M1, M1A1, M45:  

Charge	Muzzle Velocity (mps)	Max Range (m)	Elevation (mil)
1, M3, green bag	207.3	3900	774.4

3-94 Change 1

Weights

Filler material

Fuzes

# JavaScript Tool for Data Management



## Enter munition information

### Identifying info

Title	Name (*Required)
<input type="text" value="PROJECTILE, 155-MILLIMETER: SMOI"/>	<input type="text" value="155mm M116"/>

Manual	Page
<input type="text" value="TM 43-0001-28"/>	<input type="text" value="304"/>

Class

### Dimensions

Caliber as given	SI unit (m) <a href="#">guess</a>
<input type="text" value="155 mm"/>	<input type="text" value="0.155"/>

Length as given	SI unit (m) <a href="#">guess</a>
<input type="text" value="26.41 in"/>	<input type="text" value="0.670814"/>

Weight as given	SI unit (kg) <a href="#">guess</a>
<input type="text" value="94.80 lb"/>	<input type="text" value="43.000556676"/>

### Descriptors

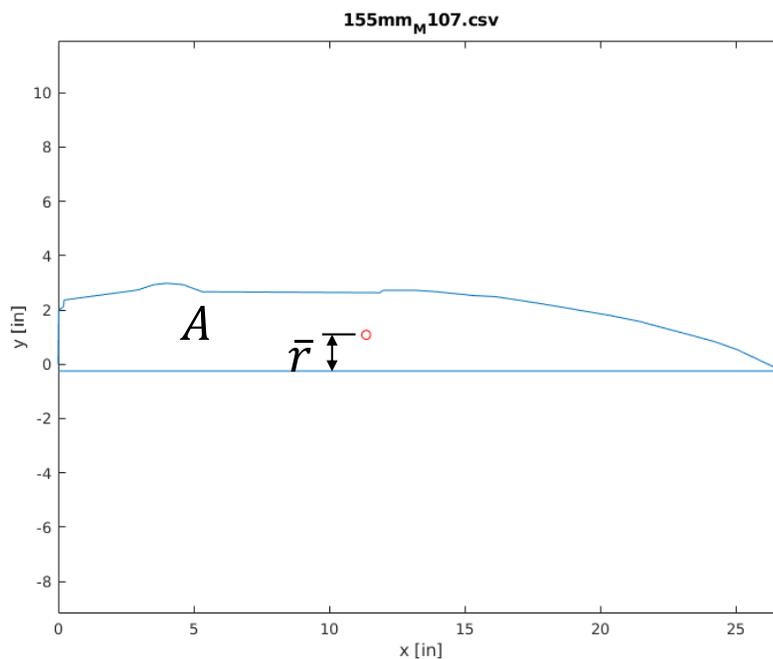
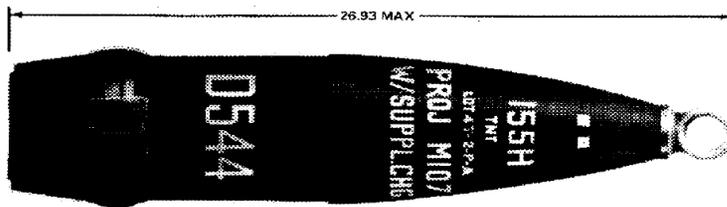
Color

Cannons used with



# Estimating Volumes of Munitions

PROJECTILE, 155-MILLIMETER: HE, M107 (NORMAL AND DEEP CAVITY)

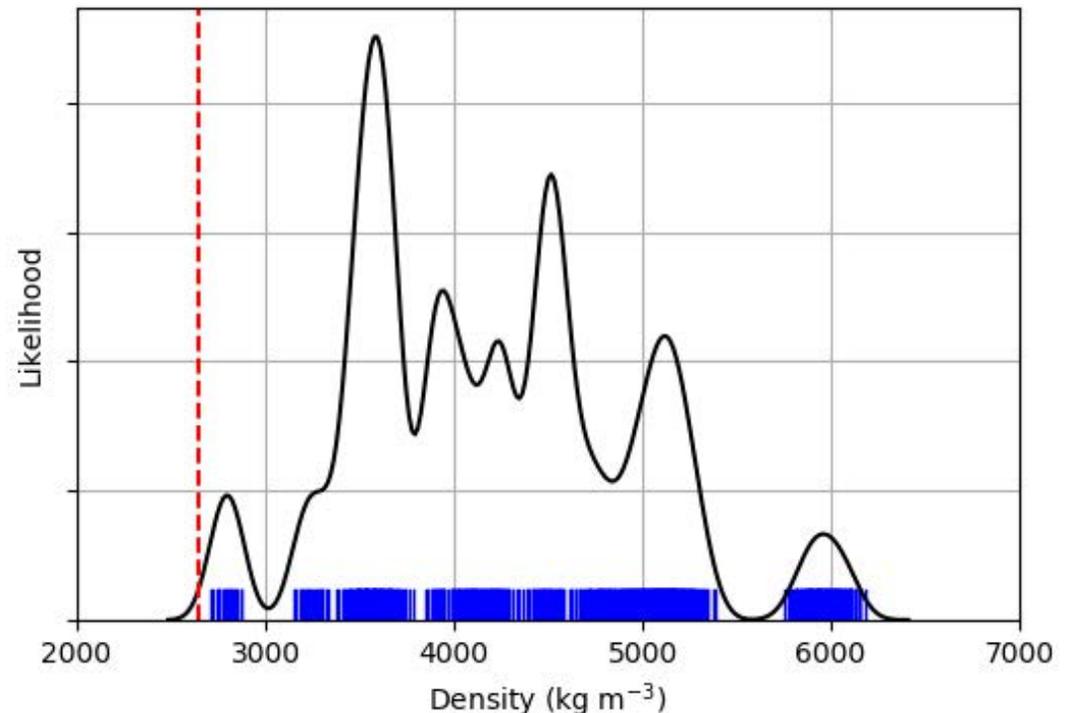


- TM 43-0001-28 has a schematic image of each munition
- The 2D outline is extracted using WebPlotDigitizer
  - ◆ Manually adjusted for poor-quality images
  - ◆ Approximating nose/fuze shape
- Matlab scripts compute the munition volume using theorems of Pappus and Guldinus
 
$$V = \theta \bar{r} A$$
- 3D scans of some munitions can be used to verify results



# Munitions Density Distributions

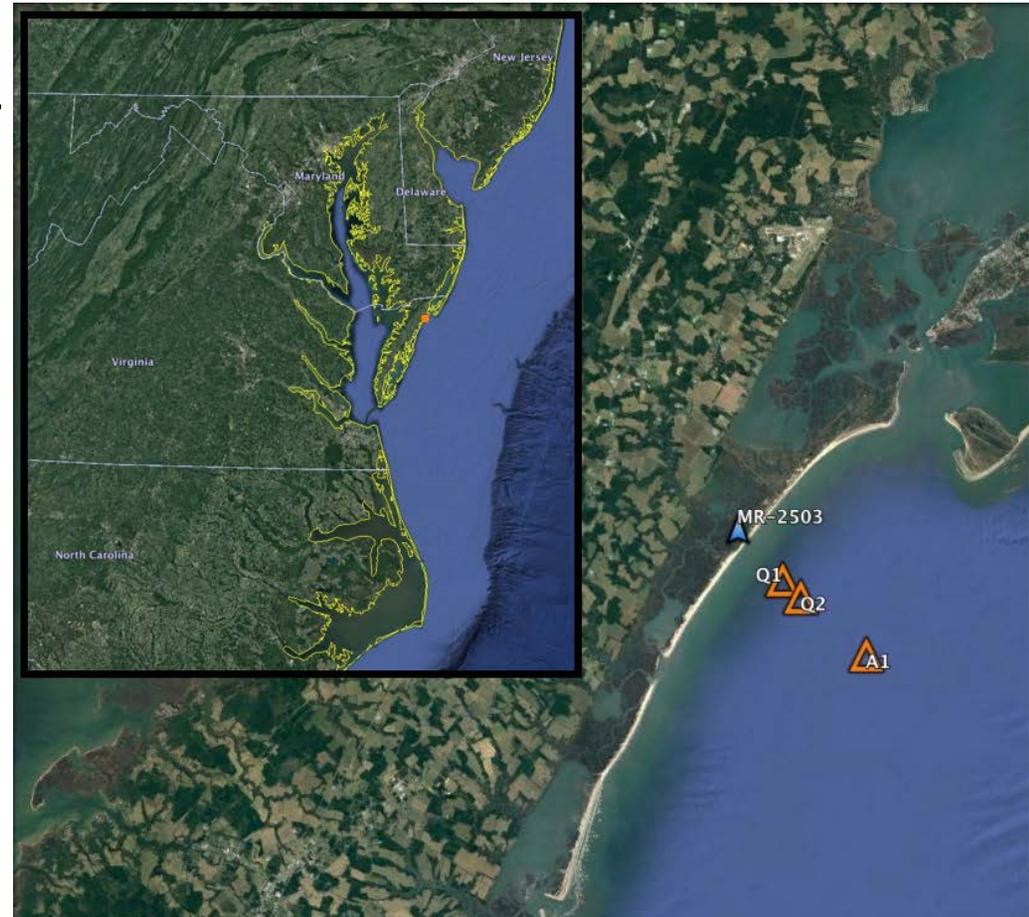
- 155 mm caliber example
- Each estimated volume is combined with all combinations of estimated weights to produce a density distribution for every entry in the manual
- Distributions for all munitions of a single caliber are combined into an overall likelihood distribution
  - ◆ Likelihood is the prior probability of a munition having a certain density



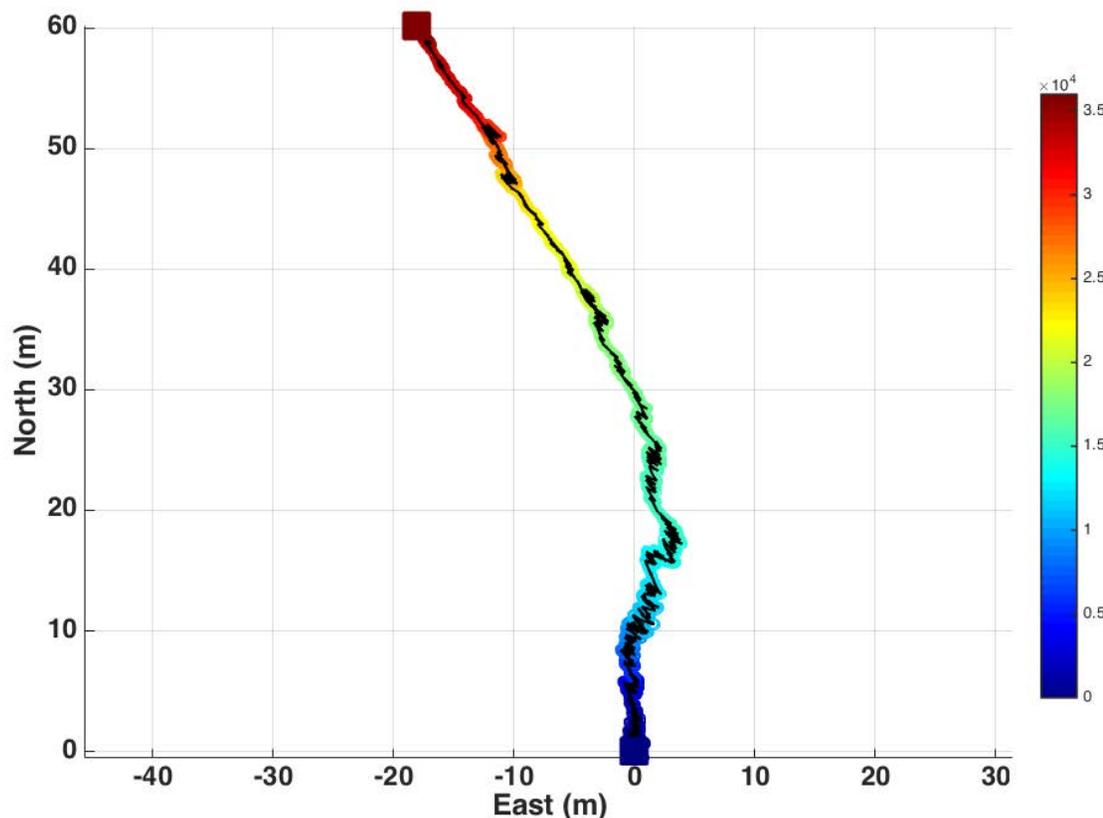
*Figure: Plot of likelihood distribution for all 155mm caliber munitions shows kernel density estimate of likelihoods (black), combination of munition “weight options” (blue) and the density of quartz sand, 2650 kg m<sup>-3</sup> (red).*

# Wallops Island Munitions Mobility Experiment WIMM-X

- Collaboration with MR-2503
- Sediment cores on 12 Jan 2017
- Deployment on 17 Feb 2017
- Maintenance on 9 Mar 2017
- Recovery on 19-20 Apr 2017
- Deployed quadpods at 9 m and 11 m water depths
- Smart munitions with IMUs logging at 16 Hz continuous
  - ◆ Three calibers at each location (81 mm, 4.2 inch, and 155 mm)

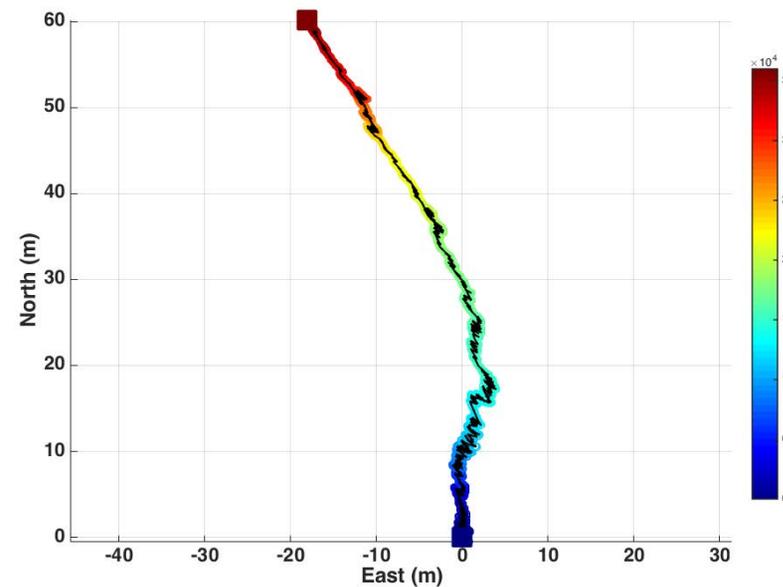
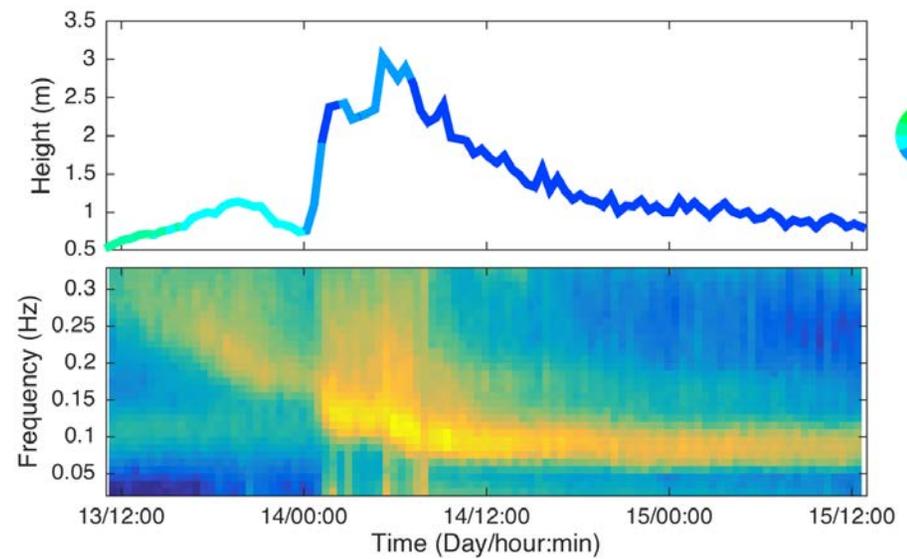
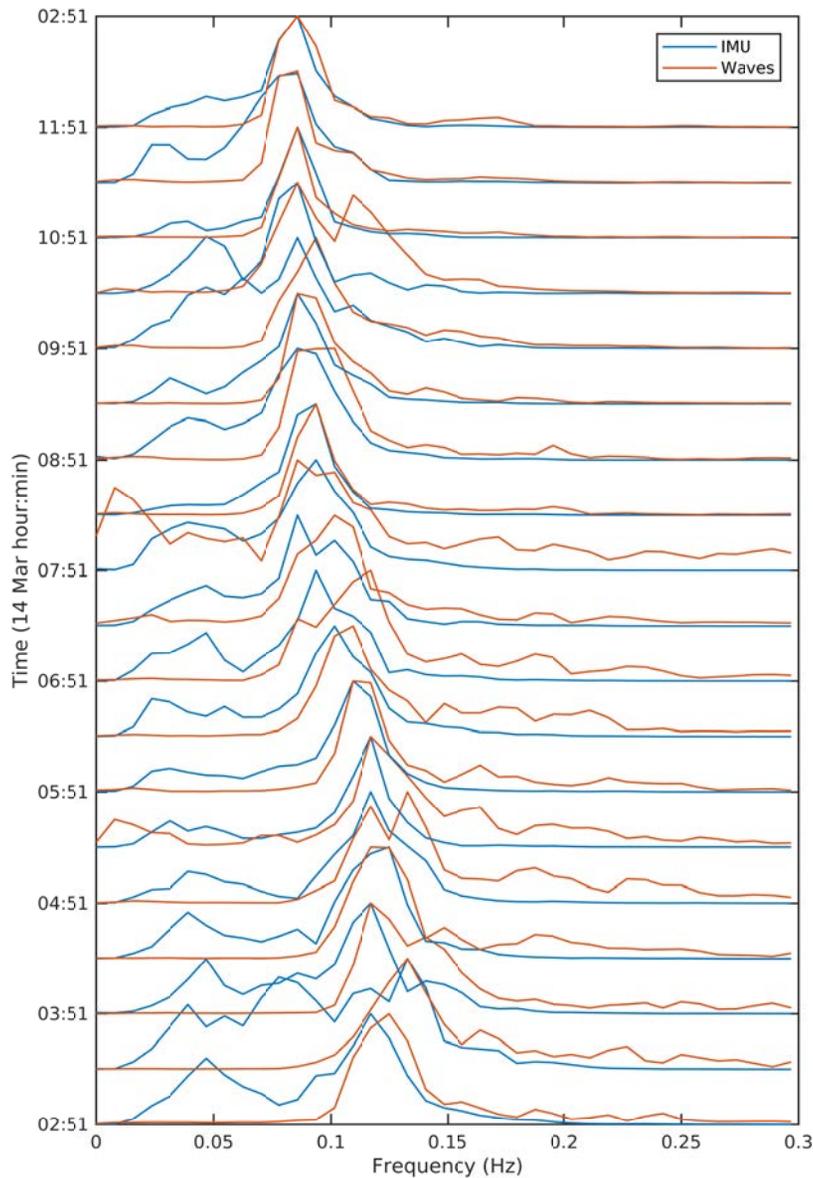


# WIMM-X Smart Munitions Mobility



- Start of mobility during storm at 14 March 2017 at 0228
- Integration interval is 9.9 hours (16 Hz continuous)
  - ◆ 570,240 points
- Peak significant wave height near 2.8 m during interval
- Total integrated displacement was 206.4 feet with 344 degree heading
- Diver measured displacement was 202.0 feet with 340 degree heading

# WIMM-X Mobility by Waves



## Ongoing WIMM-X Analysis

- Publish IMU integration results and algorithm
- Compare near bed orbital excursion length scale with high spatial frequency oscillations
- Cast observed mobility in context of bathymetry and sedimentology analysis

# Summary

- Currently in 6<sup>th</sup> year of execution for MR-2320
- Peer-reviewed publications (1 in print, 2 in review, 3 in preparation)
  - ◆ Conference proceedings (2 in print)
- Reports (1 completed and 1 outstanding)
  - ◆ Publish interim report online documenting TRESX13 experiment
  - ◆ Final Report comprehensive report
- Next steps
  - ◆ Unify laboratory and field observations
  - ◆ New SERDP proposal under review titled, “Towards Developing Demonstrations for Munitions Mobility and Burial in the Underwater Environment”

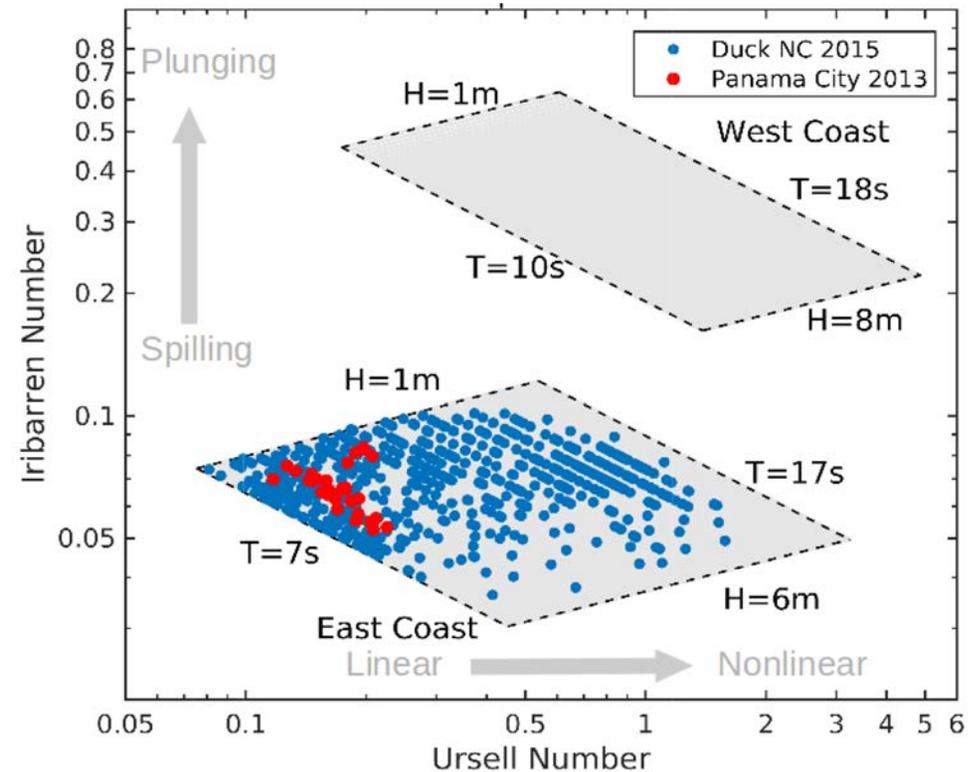
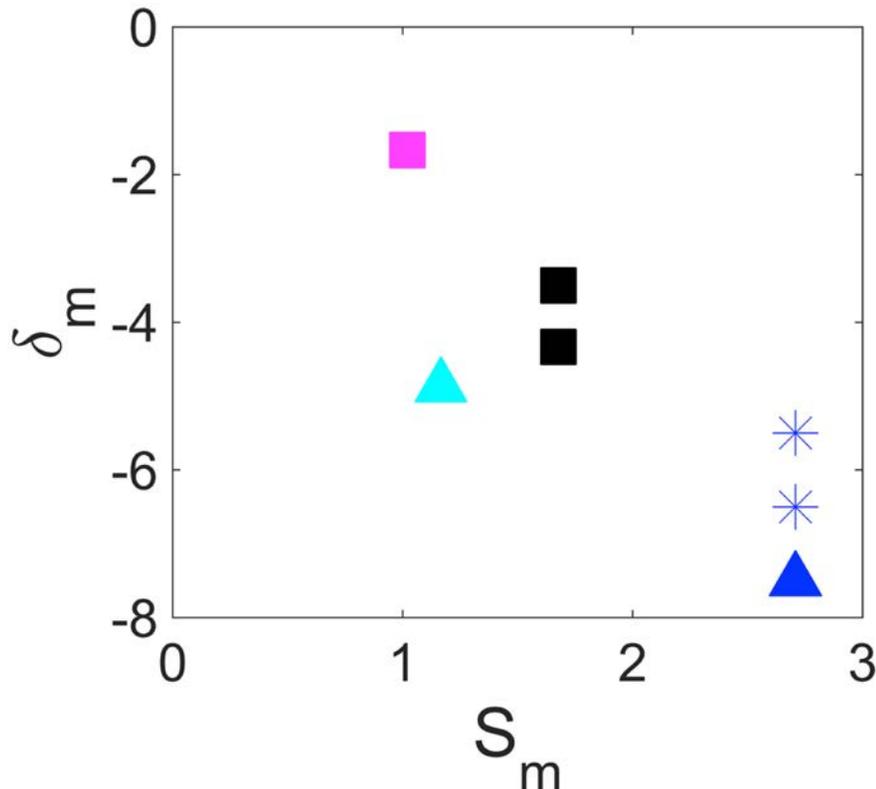
## Transition Plan

- Prepare and distribute documentation for all aspects of experimental methods, including design, fabrication, deployment, recovery, and signal processing
- Complete and distribute database of munitions characteristics including estimates of bulk density distributions
- Proposed new SERDP effort, “Towards developing demonstrations for munitions mobility and burial in the underwater environment

# Proposal to Develop Demonstrations

## Objectives:

- 1) to reduce the dimensionality of the problem



- 2) to complete our observations of the role of water wave characteristics

## Proposed CONOP for Site Managers

- Establish data collection for necessary environmental parameters for both sensor performance and mobility and burial modeling
- Perform site surveys to detect and classify munitions (i.e., map contamination)
- Run forecast/hindcast models of coupled hydrodynamics and probabilistic predictions for munitions over individual storm events
- Decide remediation versus manage in place

Demonstration of mobility and burial modeling begins with prediction and observation over single storm events

# BACKUP MATERIAL

**These charts are required, but will only be briefed if questions arise.**

# Publications

- Klammler, H., Sheremet, A., and **J. Calantoni**, *in review*, Seafloor burial of surrogate UXO by wave-induced sediment instability, *submitted to IEEE Journal of Oceanic Engineering*.
- Frank, D.P., Landry, B.J., and **J. Calantoni**, *in review*, Development of smart munitions for assessing mobility in oscillatory flows, *submitted to Journal of Atmospheric and Oceanic Technology*.
- de Moustier, C., and **J. Calantoni**, *in review*, Cross-spectrum analysis of tidal measurements offshore Panama City Beach, FL, *submitted to IEEE Journal of Oceanic Engineering*.
- Penko, A., **Calantoni, J.**, and B.T. Hefner (2017), Modeling and observations of sand ripple formation and evolution during TREX13, *IEEE Journal of Oceanic Engineering*, 42(2), 260-267.
- Frank, D.P., Landry, B.J., and **J. Calantoni** (2016), Investigating munitions mobility in oscillatory flows with inertial measurement units, OCEANS 16, *IEEE Oceanic Engineering Society*, Monterey, CA, 19-22 September.
- Calantoni, J.** (2014), Informal Workshop on Burial and Mobility Modeling of Munitions in the Underwater Environment, Final Workshop Report, SERDP and ESTCP Office, Distribution Statement A.
- deMoustier, C. and **J. Calantoni** (2014), Target detection with sector scanning imaging sonars, *Underwater Acoustics Proceedings*, edited by Papadakis and Bjorno, Rhodes, Greece, 22-27, June.

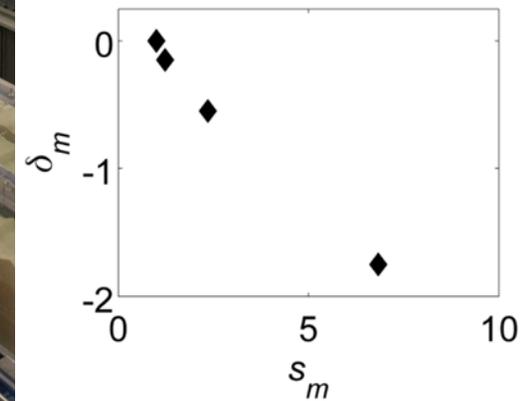
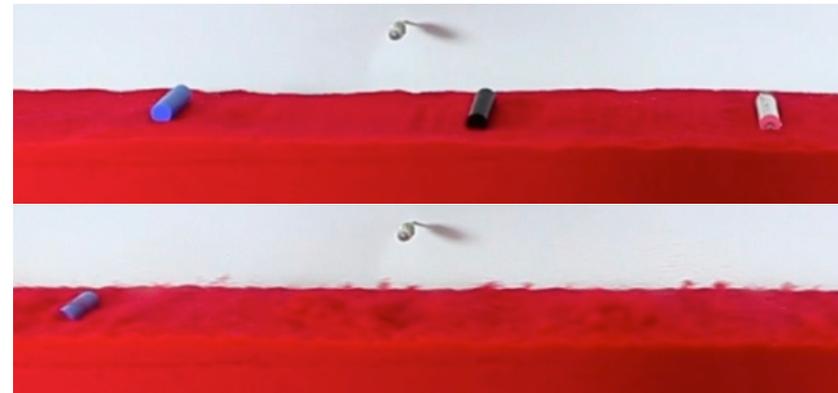
# Presentations and Events

During the last 12 months:

- 1) 3<sup>rd</sup> Informal Workshop on Munitions Mobility and Burial Modeling (co-organized)
- 2) Keynote presentation for Munitions Response session at 2017 Symposium (speaker)
- 3) Special session at the AGU Fall Meeting, “Munitions in the Underwater Environment” (convener)
- 4) Oral presentation at the Ocean Sciences Meeting on munitions burial (speaker)
- 5) NAVFAC 2018 Environmental Restoration Training (speaker)
- 6) Plenary at Mine Warfare Improvement Program (speaker)

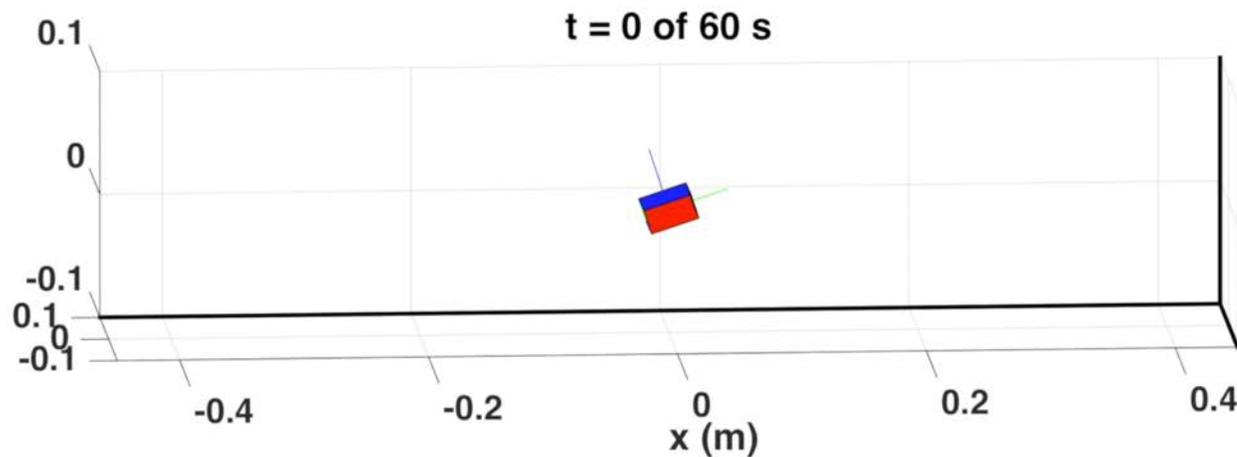
# Role of Munitions Bulk Density - Lab

- Scaled sediment density with nylon beads (0.5 mm)
- Cylindrical munitions of varying density (10 X 2 cm)
- Generated sheet flow conditions for nylon beads
  - ◆ 1 – 2 cm thick mobile layer
- Plotted non-dimensional burial depth (by diameter) versus relative density
- Need extreme storm conditions to test in the field with full scale munitions



*Sediment Dynamics Laboratory,  
Naval Research Laboratory,  
Stennis Space Center, MS*

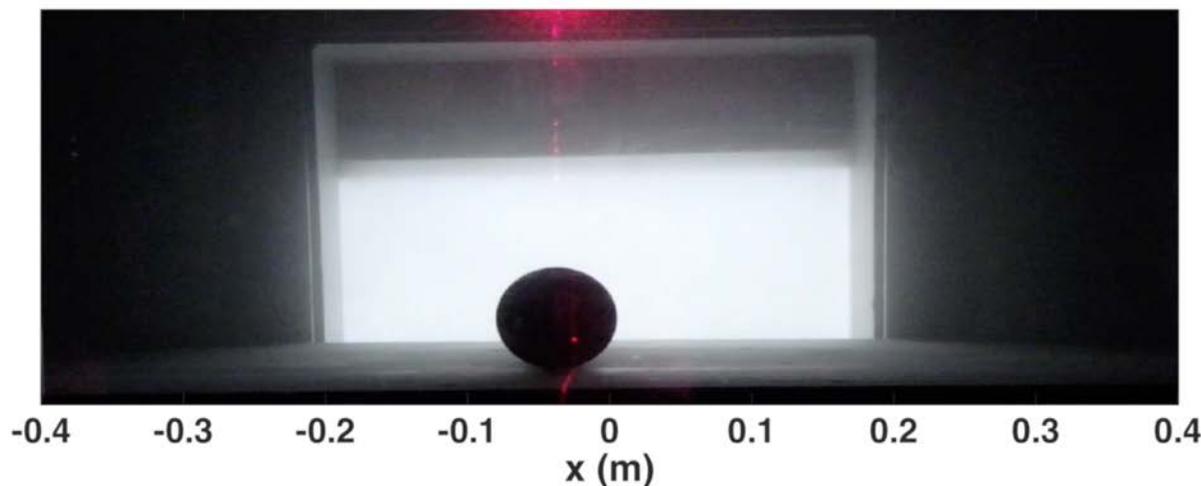
# Smart Munitions – Laboratory Testing



- Collaboration with MR-2410
- COTS IMU embedded in nose



- Large Oscillatory Water-Sediment Tunnel (UIUC)
- Laser and camera system for optical tracking



# Signal Processing Algorithm Summary

- Attitude Heading Reference System (AHRS) data fusion algorithm (proprietary x-IO code) to remove drift from gyroscope and heading
- Butterworth low pass filter to reduce noise
- Measured angular velocities are transformed from the sensor coordinate system to earth coordinates
- Binary condition for motion is set by choosing threshold values for acceleration and angular velocities
- Linear velocities are estimated from transformed and binary threshold angular velocities for rolling dominated motion
- Estimated linear velocities are low-pass filtered
- Linear velocities are numerically integrated for displacement

## Bed Failure Criteria

### **A – Critical shear stress**

Local shear failure (Mohr-Coulomb criterion)



### **B – Zero effective stress**

Cohesionless sand cannot resist tensile stresses



### **C – Zero vertical effective stress**

Localized cancelling of buoyancy plus upward seepage forces against gravity (liquefaction)



### **D – Vertical uplift of sediment column**

Similar to C, but for vertical sediment columns



### **E – Horizontal shear of sediment column**

Generalized Sleath criterion for plug flow



## WIMM-X Sedimentology

- Initial analysis performed with grab sampler
- Diver push cores at instrument locations during deployment, maintenance, and recovery
- Cores at Q1 location have been analyzed